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A PERTURBATION SOLUTION FOR THE NONLINEAR RADIATION

HEAT TRANSFER PROBLEM

by

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## A PERTURBATION SOLUTION FOR THE NONLINEAR RADIATION

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#### Abstract

A perturbation technique is developed for determining the transient temperature in a slab, insulated on one face and subject to nonlinear thermal radiation at the other face. The slab is initially at a uniform temperature and is assumed to be homogeneous and isotropic; the physical properties are assumed to be independent of temperature. Temperature distributions and heat flux at the radiating boundary are presented in a dimensionless, graphical form for a wide range of parameters, and the former are compared with previously obtained analog computer results.

#### Das Abstrakt

Eine Perturbationsmethode für die Ermittlung des Zeitverlaufs von Temperatur in einer Platte, die an einer Oberfläche isoliert und an der anderen einer nichtlinearen Wärmestrahlung unterworfen ist, wird entwickelt. Es wird vorausgesetzt, dass die Platte ursprünglich eine gleichmässige Temperatur hat, und dass sie homogen und isotropisch ist; ausserdem wird vorausgesetzt, dass die physikalischen Eigenschaften von der Temperatur unabhängig sind. Die Temperaturverbreitungen und die Wärmestromung an der strahlenden Oberfläche sind für eine umfangreiche Parameterreihe in einer graphischen dimensionsfreien Form dargestellt, und jene sind mit den früher an Amalogrechenmaschinen erhaltenen Resultaten verglichen.

## Краткий обзор

В этом докладе разрабативается пертурбационный метод для установления зависимости температури в слое, который изолирован на одной поверхности и подвергнут нелинейной термической радиации на другой. Слой начально имеет равномерную температуру и предполагается, что он однородный и изотермический; кроме того, его физические свойства предполагаится независимыми от температури. Распределения температури и тепло-потока через радиационную поверхность заданы в безразмерной графической форме для широкого диапазона параметров, и приведено сравнение с результатами полученными заранее при помощи вичислительных машин.

Introduction In problems of heat transfer involving convection, radiation, or evaporation at the surface of a body, the flux of heat at the surface temperature is, in general, a nonlinear function of the surface temperature. Furthermore, the thermal properties of the body may also vary with temperature. One commonly employed approximation to the real phenomenon assumes constant properties in the medium but with heat transfer at the surface a given nonlinear function of surface temperature. Mathematically such problems occupy an interesting position between the classical linear theory and the general case in which both the differential equation and the boundary conditions are nonlinear.

In heat transfer between solids and gases it

is commonly assumed that the rate of heat exchange across a gas-solid interface is proportional to the difference between the temperature of the solid surface and the surrounding medium which gives rise to the boundary condition of the form<sup>1</sup>

$$-k \left(\frac{\partial T}{\partial m}\right) = H\Delta T \tag{1}$$

where  $\partial T/\partial x$  is the thermal gradient at the surface; and H is a factor of proportionality, frequently called the film transfer factor; and k is the thermal conductivity. If H is independent of temperature the above boundary condition is linear. For small temperature differences,  $\Delta T$ ,

<sup>1</sup>This is, of course, "Newton's law of cooling."

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and where most of the heat transfer is due to conduction-convection, H varies but slightly with temperature and may be approximated by some constant number. For large temperature differences radiation plays a dominant role so that the film transfer factor is strongly temperature dependent. When the conduction and convection may be neglected, the film transfer factor is given by Stefan-Boltzmann Radiation Law,

$$H_r = A \in \frac{T_s^4 - T_g^4}{T_g - T_g}$$
(ii)

where  $T_g$  is the absolute temperature of the solid at the surface,  $T_g$  the absolute temperature of the ambient gas,  $\in$  the emissivity, and A is a constant depending upon the units of measurement. It is clear that when the film coefficient for the radiating boundary (ii) is substituted in (i) the resulting boundary condition is nonlinear. Since a nonlinearity in either the differential equation or the boundary condition renders the entire boundary value problem nonlinear, the solution to the unsteady heat transfer problem with a radiating boundary condition is difficult.

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The present problem was studied by Mann and Wolf (1); their investigation was, however, primarily concerned with the existence and uniqueness of the solution to the integral equation associated with the problem and less concerned with a practical method for its solution. Jaeger (2) solved the problem in terms of a power series expansion which is adequately convergent only for early times. Chambre (3) obtained a solution in terms of an approximating polynomial evaluated by means of the "heat balance" integral. Abarbanel (4) presents approximate solutions for the surface temperature of slabs, spheres, cylinders, and semi-infinite solids, for very small and large values of time. Richardson (5) utilizes the Biot variational method and a polynomial approximation to obtain an approximate solution for a narrow range of exponents in the nonlinear boundary condition. Fairall, et al, (6) present some computer results for surface temperatures. A great quantity of data for this problem has been obtained by Zerkle and Sunderland (7) who have obtained the numerical results by the use of an analog computer and have plotted graphs for a wide range of parameters.

Despite the extensive amount of work previously done on this problem there is yet no general analytical solution available. In the present study an asymptotic solution is obtained, by means of a perturbation procedure, which appears to be satisfactory for most engineering purposes. The large number of graphs provided by Zerkle and Sunderland provide a convenient standard for demonstrating the relative accuracy of the present solution. Because the latter is analytical, important functions of the temperature distribution such as flux at any point and total heat are readily obtained.

Statement of the Problem A slab initially at a uniform temperature is suddenly exposed to radiant heat transfer on one or both faces. It is assumed, following ref. (7) that the boundary conditions are uniform over each boundary surface (this implies that the heat flow is one-dimensional); the environment temperature  $(T_e)$  is constant; the slab is a homogeneous, isotropic, and opaque, and the physical properties are independent of temperature; the radiation interchange factor  $(F_{se})$  is independent of slab surface temperature; the slab is exposed to continual heating. From the first assumption, the general heat conduction equation reduces to

$$\frac{\partial \mathbf{T}}{\partial \tau} = \frac{\mathbf{k}}{\rho c} \quad \frac{\partial^2 \mathbf{T}}{\partial \mathbf{x}^d}$$

$$(0 \le \mathbf{x} \le \mathbf{L}; \ \tau > 0) \qquad (1)$$

A solution to equation (1) subject to the following initial and boundary conditions is sought.

$$T(x,0) = T_i$$
 (2)

$$\frac{\partial \mathbf{T}}{\partial \mathbf{x}} (0, \tau) = \frac{\sigma \mathbf{F}_{S\Theta}}{k} \left[ \mathbf{T}^{4}(0, \tau) - \mathbf{T}_{E}^{4} \right]$$
(3)

$$\frac{\partial \mathbf{T}}{\partial \mathbf{x}} (\mathbf{L}, \tau) = \frac{\sigma \mathbf{F}_{ge}}{k} [\mathbf{T}_{e}^{4} - \mathbf{T}^{4} (\mathbf{L}, \tau)]$$
(4)

<u>Outline of Perturbation Technique</u> It is easily shown that there exists a steady state solution, corresponding to  $\tau = \infty$ , for the above problem, as follows,

As  $\partial T/\partial \tau = 0$ , equation (1) becomes

$$T = Ax + B.$$
 (5)

Since T must satisfy the boundary conditions, substituting (5) in (3) and (4) gives

$$\frac{\partial T}{\partial \mathbf{x}}(0,\tau) = \mathbf{A} = \frac{\sigma \overline{\mathbf{F}}_{Se}}{k} \left[\mathbf{B}^4 - \mathbf{T}_{E}^4\right] \tag{6}$$

$$\frac{\partial T}{\partial x} (L,\tau) = A = \frac{\sigma F_{Be}}{k} [T_e^4 - (AL + B)^4]$$
(7)

The constants A and B are obtained by solving the algebraic equations (6) and (7) so that (1) is determined. This solution will be designated by  $T(\circ)$ .

The zeroth approximation in the perturbation technique is taken to be latter solution,  $T(\circ)$ . Further, let the first approximation be written

$$\mathbf{r}^{(1)} = \mathbf{r}^{(0)} + \varphi_1 \tag{8}$$

where it is assumed that

$$\mathbf{o}_{\mathbf{x}}(\mathbf{x},\tau) \left| < \mathbf{T}^{(\mathbf{o})}(\mathbf{x}) \right|$$
(9)

Substituting (8) into (1), (2), (3) and (4), yields a boundary-value problem on  $\varphi_1$ . After solving for  $\varphi_1$  the second approximation may be found, in principle, by perturbing  $T^{(1)}$ 

 $= T(o) + \phi_1 + \phi_2$ 

$$T^{(2)} = T^{(1)} + \varphi_2$$
 (10)

In general, however, the solution for  $\varphi_1$  will be an infinite series, where the second and subsequent terms decay at a faster rate than the first. The perturbation, therefore, is taken about  $T^{(O)} + \varphi_1'$ , which results in a second approximation

$$\mathbf{T}^{(2)} = \mathbf{T}^{(0)} + \phi_1' + \phi_2 \tag{11}$$

where  $\varphi_1'$  is the first term of  $\varphi_1$ .<sup>1</sup>

Assuming further that  $|\varphi_2| < |\varphi_1'|$  and  $|\varphi_1| < T_e$  as previously,<sup>2</sup> one obtains a boundary-value problem on  $\varphi_2$ . Proceeding to n<sup>th</sup> approximation, and in a like manner retaining the first term of each of the (n-1) solutions which is assumed to satisfy

$$|\varphi_n| < |\varphi'_{n-1}| < \dots < |\varphi'_1| < T_e$$
 (12)

yields

$$T^{(n)} = T_e + \varphi'_1 + \varphi'_2 + \dots + \varphi'_{n-1} + \varphi_n$$
 (13)

to obtain  $\phi_n$  once  $\phi_1', \, \phi_2' \, \dots , \phi_{n-1}'$  are known, one proceeds as follows. Let

$$\varphi_n = T^{(n)} - (T_e + \varphi'_1 + \varphi'_2 + \dots + \varphi'_{n-1})$$
 (14)

.Substituting the derivatives of  $\phi_n$  in (1) and (2), and realizing that each  $\phi_k'$  and  $T_e$  satisfies the heat equation, the equation on  $\phi_n$  is

$$\frac{\partial \varphi_n}{\partial \tau} = \alpha \frac{\partial^2 \varphi_n}{\partial x^{\mathbf{a}}}$$
(15)

with the initial condition

$$\varphi_{n}(\mathbf{x}, \mathbf{o}) = (T_{i} - T_{e}) - \varphi_{i}'(\mathbf{x}, \mathbf{o}) - \varphi_{2}'(\mathbf{x}, \mathbf{o}) \dots \dots - \varphi_{n-1}'(\mathbf{x}, \mathbf{o}) \qquad (16)$$

Substituting the derivatives of  $\varphi_n$  into (3) and (4) and expanding the right hand by means of the binomial expansion, taking (12) into account and retaining only those terms of order  $\varphi_n$  yields,

$$\frac{\partial \varphi_n}{\partial x} (o, \tau) = F_1(T_e, \varphi_1', \dots, \varphi_{n-1}') - k_g \varphi_n \qquad (17)$$

$$\frac{\partial \phi_n}{\partial x} (L,\tau) = F_2(T_e, \phi'_1, \dots, \phi'_{n-1}) - k_s \phi_n \qquad (18)$$

The equations (15), (16), (17), and (18) represent a linear boundary-value problem on  $\varphi_n$  with the  $\varphi'_k$  (k < n) appearing as nonhomogeneous terms. This problem is readily solved in closed

<sup>1</sup> The remainder of the series reappears in the evaluation of  $\varphi_2$ . For the numerical example considered later on, the terms of the series are proportional to  $e^{-\delta_1}$  NFo,  $e^{-\delta_2}$  NFo, etc., where  $\delta_1 < \delta_2 < \ldots$ .

" The assumptions regarding the relative magnitudes are verified a posteriori. form for each approximation provided the functions  $\varphi_{\mathbf{x}}$  are known, i.e., if one wanted the third approximation, it would be necessary to have first solved for the second and first approximation. The solutions for the various approximations will now be developed. Inasmuch as the specific example to be evaluated in the following section will be for the problem solved numerically by Zerkle and Sunderland (7), the development will be for the boundary value problem considered by them, namely: (1), (2), (4), and at  $\mathbf{x} = 0$ ,

$$\frac{\partial T}{\partial x} = 0$$
 (19)

# SOLUTION FOR VARIOUS APPROXIMATIONS

First Approximation Write

$$T(\mathbf{x},\tau) = T_{e} + \varphi_{1}(\mathbf{x},\tau)$$
(21)

where it is assumed that  $|\varphi_1(\mathbf{x}, \tau)| < T_{\rm e}$ . Substituting for T, and its derivatives from (21) in the original equation (1) and boundary conditions (2), (3) and (4) gives

$$\frac{\partial \varphi_1}{\partial \tau} = \alpha \frac{\partial^2 \varphi_1}{\partial x^2} (x, \tau) \qquad (0 \le x \le L, \tau > 0) \quad (22)$$

$$\varphi_1(x,0) = (T_1 - T_e)$$
 (23)

$$\frac{\mathrm{d}\varphi_{1}}{\mathrm{d}x}\left(0,\tau\right)=0\tag{24}$$

$$\frac{\partial \varphi_{1}}{\partial \mathbf{x}} \quad (\mathbf{L}, \tau) = \frac{\sigma F_{se}}{k} \left[ \mathbf{T}_{e}^{4} - (\mathbf{T}_{e} + \varphi_{1} (\mathbf{L}, \tau)^{4} \right]$$

$$= \frac{\sigma F_{se}}{k} \left[ \mathbf{T}_{e}^{4} - (\mathbf{T}_{e}^{4} + \mathbf{L}_{e}^{3} \varphi_{1} + 6\mathbf{T}_{e}^{2} \varphi_{1}^{2} + \mathbf{L}_{e} \varphi_{1}^{3} + \varphi_{1}^{4} \right]$$

$$= -\frac{\sigma F_{se}}{k} \mathbf{T}_{e}^{4} \left[ \mathbf{L}_{Te}^{\varphi_{1}} + 6(\frac{\varphi_{1}}{Te})^{2} + \mathbf{L}_{e}(\frac{\varphi_{1}}{Te})^{3} + (\frac{\varphi_{1}}{Te})^{4} \right] \quad (25)$$

Under the a priori assumption  $\left|\phi_{1}\right| < T_{e},$  the following is valid:

$$(\frac{\phi_1}{T_e})^3 < (\frac{\phi_1}{T_e})^2 < (\frac{\phi_1}{T_e}) < 1$$

Hence it is clear that if  $\left|\frac{\varphi_1}{T_e}\right| < \frac{2}{3}$  that the first

<sup>1</sup> There are actually four possible solutions for  $T(\circ)$  since the latter is obtained from  $[T(\circ)]^4 = T_e^4$ . The other three roots, however, are not physically meaningful.

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term on the right hand side of (25) will be the dominant one, and for small values of  $|\phi_1/T_{\rm e}|$  all but the first term may be neglected. Thus (25) becomes

$$\frac{\partial \varphi_{\mathbf{h}}}{\partial \mathbf{x}} (\mathbf{L}, \tau) = - \mathfrak{h} \left( \frac{\sigma F_{\mathrm{Se}}}{k} \mathbf{T}_{\mathrm{e}}^{3} \right) \varphi_{\mathbf{h}}$$
$$= - \frac{\mathfrak{h}}{\mathrm{LN}_{\mathrm{rh}}} \varphi_{\mathbf{h}}$$
$$= - \mathbf{k}_{\mathrm{e}} \varphi_{\mathrm{e}} \quad \text{where } \mathbf{k}_{\mathrm{e}} \equiv -\frac{\mathfrak{h}}{\mathrm{L}} \qquad (26)$$

$$= -k_{5} \phi_{1} \text{ where } k_{5} = \frac{1}{LN_{rh}}$$
The problem, as it stands, is equivalent to

the case of a heated slab of thickness L which is initially at temperature  $T_i$  and which has one face (x = 0) insulated, while the surface at x = L of the slab is heated according to Newton's Law of heating (linear radiation). The general solution of equation (22) is easily obtained, Chapman (8), and is

 $\mathbf{\phi}_{\mathbf{1}} = e^{-\beta^2 \alpha \tau} [B_1 \sin(\beta x) + B_2 \cos(\beta x)]$ (27)

where ( $\beta L$ ) tan ( $\beta L$ ) =  $\frac{l_i}{N_{rh}}$  defines the value of  $\beta$  i.e.  $\delta_n \tan \delta_n = \frac{l_i}{N_{rh}}$  where  $\delta_n = (\beta L)$  (28)

Using the (23), (24), (26), (27), the solution for  $T^{(1)}$  is<sup>1</sup>

$$\frac{\mathbf{T}^{(\mathbf{1})} - \mathbf{T}_{\mathbf{i}}}{\mathbf{T}_{\mathbf{e}} - \mathbf{T}_{\mathbf{i}}} = 1 - 2\sum_{n=1}^{\infty} e^{-\delta_n^2 \alpha \tau} \frac{\sin \delta_n \cos(\delta_n \xi)}{\delta_n + \sin \delta_n \cos \delta_n} (29)$$

where  $\delta_n$  is the n<sup>th</sup> root of the equation (28), values of which have been evaluated and are tabulated in Carslaw and Jaeger (9).

Second Approximation Since (29) involved an approximation (i.e.  $|\phi_1/T_e| < 1$ ) it does not re present, of course, a general solution for the transient problem.<sup>2</sup> To obtain a closer approximation, for larger values of  $|\phi_1/T_e|$ , (29) is perturbed, i.e.,  $T = T_e + \phi_1 + \phi_2$ . (30)

As noted earlier, because of the decay factor, all terms but the first are negligible for large times. Moreover, since one is quite free to choose the value about which to perturb, rather than include all of  $\varphi_1$  in the second approximation only its first term is retained. Denoting the first term of  $\varphi_1$  series by  $\varphi_1'$ , (30) becomes

$$\mathbf{T} = \mathbf{T}_{\mathbf{e}} + \boldsymbol{\varphi}_{\mathbf{1}}' + \boldsymbol{\varphi}_{\mathbf{2}} \tag{31}$$

where it is assumed that  $\left|\phi_{2}/T_{e}\right|<\left|\phi_{1}\right.'/T_{e}\right|$  and where

$$\varphi_{I} = 2e^{-\delta_{I}^{*}\alpha \tau/L^{*}} \frac{\sin \delta_{I} \cos(\delta_{I} \xi)}{\delta_{I} + \sin \delta_{I} \cos \delta_{I}} (T_{i} - T_{e}) \quad (32)$$

The variable  $\frac{T^{(1)} - T_i}{T_e - T_i}$  has been selected to conform to (7).

The solution obviously fails at  $\tau = 0$ .

Substituting (31) and its derivatives into (1), (2), (3), and (4) yields, after symplifying,

$$\frac{\partial \phi_2}{\partial \tau} = \alpha \frac{\partial^3 \phi_2}{\partial x^2} \qquad (0 \le x \le L, \tau > 0) \qquad (33)$$

 $\varphi_2(\mathbf{x},0) = (T_i - T_e) - \varphi_1'(\mathbf{x},0)$ 

$$= (T_{i} - T_{e}) - 2 \frac{\sin \delta_{1} \cos(\delta_{1} \xi)}{\delta_{1} + \sin \delta_{1} \cos \delta_{1}} (T_{i} - T_{e})$$

$$= (T_{i} - T_{e}) - k_{1} \cos(\delta_{1}\xi)(T_{i} - T_{e}) \quad (34)$$

$$\frac{\partial \phi_2}{\partial \mathbf{x}} \left( \mathbf{0}, \mathbf{\tau} \right) = \mathbf{0} \tag{35}$$

 $\frac{\partial \mathbf{T}}{\partial \mathbf{x}} (\mathbf{L}, \tau) = \sigma \mathbf{F}_{se} [\mathbf{T}_{e}^{4} - \mathbf{T}^{4} (\mathbf{L}, \tau)]$ 

i.e. 
$$\frac{\partial \varphi_{1}}{\partial x}'(L,\tau) + \frac{\partial \varphi_{2}}{\partial x}(L,\tau) = \frac{\sigma F_{Be}}{k} [T_{e}^{4} - T^{4}(L,\tau)]$$
  
i.e.  $-\frac{\sigma F_{Be}}{k} (\mu T_{e}^{3}) \varphi_{1}' + \frac{\partial \varphi_{2}}{\partial x} (L,\tau)$   
 $= \frac{\sigma F_{Be}}{k} [T_{e}^{4} - [T_{e} + (\varphi_{1}' + \varphi_{2})]^{4}]$  (36)

As with the first approximation only the terms of order  $\phi_2$  are retained, which reduces (36) to the linear equation

$$\frac{\partial \varphi_2}{\partial \mathbf{x}} (\mathbf{L}, \tau) = -6 \frac{\sigma \mathbf{F}_{se}}{\mathbf{k}} \varphi_1 {}^{\prime 2} \mathbf{T}_{e}{}^{3} - \frac{h}{\mathbf{k}} \frac{\sigma \mathbf{F}_{se}}{\mathbf{k}} \mathbf{T}_{e}{}^{3} \varphi_2$$

$$= -6(\frac{\sin 2\delta_1}{\delta_1 + \sin \delta_1 \cos \delta_1})^{2} \frac{(\mathbf{T}_1 - \mathbf{T}_{e})^{2}}{\mathbf{T}_{e} \mathbf{LN}_{rh}}^{2} e^{-\mathbf{k}_2 \tau}$$

$$= -\frac{\mu}{\mathbf{LN}_{rh}} \varphi_2$$

$$= -\mathbf{k}^{(1)} \cdot e^{-\mathbf{k}_2 \tau} - \mathbf{k}_{s} \varphi_3 \qquad (37)$$

where

$$\mathbf{k}^{(1)} = 6(\frac{\mathrm{Sin}2\delta_1}{\delta_1 + \mathrm{Sin}\delta_1 \cos\delta_1})^2 \frac{(\mathrm{T}_1 - \mathrm{T}_2)^2}{\mathrm{T}_2 \mathrm{LNrh}}, \ \mathbf{k}_2 = 2\delta_1^2 \frac{\alpha}{\mathrm{L}^2}$$

While the restrictions on  $\varphi_2$  are similar to that formerly imposed on  $\varphi_1$  (in the discussion of the first approximation), at this point it is no longer required that  $|\varphi_1/T_e|$  (or  $|\varphi_1'/T_e|$ ) be vanishingly small.

Solution for Second Approximation What appears the simplest way to effect a solution of (33), (34), (35), and (37) is to let

$$\varphi_2(\mathbf{x},\tau) = \zeta(\mathbf{x},\tau) + f_1(\mathbf{x})g_1(\tau)$$
 (38)

which after substitution gives

$$\alpha \zeta_{XX} = \zeta_{T}(X, \tau) - \{ \alpha f_{1}'' g_{1} - f_{1} \dot{g}_{1} \}$$
(39)

$$C_{\tau}(0,\tau) + f_{1}'(0)g_{1}(\tau) = 0$$
(40)

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$$\begin{aligned} \boldsymbol{\zeta}_{\mathbf{X}}(\mathbf{L},\tau) + \mathbf{f}_{1}'(\mathbf{L})\boldsymbol{g}_{1}(\tau) + \mathbf{k}_{\mathbf{g}}\boldsymbol{f}_{1}(\mathbf{L})\boldsymbol{g}_{1}(\tau) \\ &= -\mathbf{k}^{(1)}\boldsymbol{e}^{-\mathbf{k}_{\mathbf{g}}\tau} - \mathbf{k}_{\mathbf{g}}\boldsymbol{\zeta}(\mathbf{L},\tau) \end{aligned}$$

Since  $f_1(x)$  and  $g_1(\tau)$  are arbitrary functions they are chosen such that

$$g_1(\tau)[f_1'(L) + k_g f_1(L)] = -k^{(1)}e^{-k_g \tau}$$
 (42)

from which it follows from (41) that

$$\mathbf{L}_{\mathbf{L}}(\mathbf{L}_{\mathbf{T}}) = -\mathbf{k}_{\mathbf{E}} \zeta(\mathbf{L}_{\mathbf{T}})$$

Further, it is convenient to let

$$f_1'(L) + k_5 f_1(L) = 1$$
 (43)

so that 
$$g_1(\tau) = -k^{(1)}e^{-K_2\tau}$$
 (44)

Furthermore choose 
$$f'(0) = 0$$
 (45)

then (40) becomes 
$$\zeta_{\mathbf{X}}(0, \tau) = 0$$
 (40)

Finally let 
$$\alpha f_1 g_1 - f_1 g_1 = 0$$
 (47)

so that (39) becomes 
$$\alpha \zeta_{XX} = \zeta_T$$
 (40)

Substituting (44) into (47) gives

$$\alpha f_1''(-k^{(1)}e^{-k_s \tau}) - f_1(k_s k^{(1)}e^{-k_s \tau}) = 0$$
 and upon

dividing by 
$$k_4 e^{-k_2 \tau}$$
 yields  $\alpha f_1'' + k_2 f_1 = 0$  (49)

From the boundary conditions on  $f_1$ , (43), (45), and (47), the solution for  $f_1$  becomes

$$f_1(x) = \frac{\cos qx}{k_g \cos q - q \sin q} \quad \text{where } q = \sqrt{k_2} \qquad (50)$$

Substituting (38) for  $\varphi_2$  in the initial condition (34) gives for the initial condition on  $\zeta$ 

$$\zeta(\mathbf{x},0) = (T_{1}-T_{e}) - k_{1} \cos(\delta_{1}\xi) + k^{(1)} \frac{\cos qx}{k_{g} \cos ql - q \operatorname{Sinql}}$$
(51)

Hence the completion of the solution for  $\varphi_2$  requires the solution of

$$\alpha \zeta_{\tau \tau \tau}(\mathbf{x}, \tau) = \zeta_{\tau}(\mathbf{x}, \tau) \tag{52}$$

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$$\boldsymbol{\zeta(\mathbf{x},0)} = (\mathbf{T}_{1} - \mathbf{T}_{0}) - \mathbf{k}_{1} \operatorname{Cos}(\delta_{1} \boldsymbol{\xi}) \\ + \mathbf{k}_{4} \frac{\operatorname{Cosqx}}{(\mathbf{k}_{g} \operatorname{Cosql} - q\operatorname{Sinql})}$$
(53)

$$\zeta_{\mathbf{T}}(\mathbf{0},\mathbf{T}) = \mathbf{0} \tag{54}$$

$$\zeta_{\tau}(\mathbf{L},\tau) = -\mathbf{k}_{\mathbf{B}} \zeta(\mathbf{L},\tau) \tag{55}$$

(52)-(55) is similar to the boundary-value problem on  $\varphi_1$  and may be solved in an identical fashion, ref. (8), to yield

$$\begin{aligned} \mathbf{s}(\mathbf{x}, \mathbf{\tau}) &= 2 \sum_{\mathbf{n}=1}^{\infty} e^{-\delta_{\mathbf{n}}^{2} \mathbf{W} \mathbf{r} \mathbf{o}} \frac{\sin \delta_{\mathbf{n}} \cos(\delta_{\mathbf{n}} \mathbf{S})}{\delta_{\mathbf{n}}^{+} \sin \delta_{\mathbf{n}} \cos \delta_{\mathbf{n}}} (\mathbf{T}_{\mathbf{i}} - \mathbf{T}_{\mathbf{e}}) \\ &- 2 \sum_{\mathbf{n}=1}^{\infty} \delta_{\mathbf{n}} e^{-\delta_{\mathbf{n}}^{2} \mathbf{N} \mathbf{F} \mathbf{o}} \frac{\cos(\delta_{\mathbf{n}} \mathbf{S})}{\delta_{\mathbf{n}}^{+} \sin \delta_{\mathbf{n}} \cos \delta_{\mathbf{n}}} \\ &\cdot \frac{\mathbf{k}_{\mathbf{i}}}{2} \left[ \frac{\sin(\delta_{\mathbf{i}} + \delta_{\mathbf{n}})}{(\delta_{\mathbf{i}} + \delta_{\mathbf{n}})} + \frac{\sin(\delta_{\mathbf{i}} - \delta_{\mathbf{n}})}{(\delta_{\mathbf{i}} - \delta_{\mathbf{n}})} \right] + 2 \sum_{\mathbf{n}=1}^{\infty} \delta_{\mathbf{n}} \\ &\cdot e^{-\delta_{\mathbf{n}}^{2} \mathbf{N} \mathbf{F} \mathbf{o}} \frac{\cos(\delta_{\mathbf{n}} \mathbf{S})}{\delta_{\mathbf{n}} + \sin \delta_{\mathbf{n}} \cos \delta_{\mathbf{n}}} \frac{\mathbf{k}_{\mathbf{G}}}{2} \\ &\cdot \left[ \frac{\sin(q + \delta_{\mathbf{n}})}{(q + \delta_{\mathbf{n}})} + \frac{\sin(q - \delta_{\mathbf{n}})}{(q - \delta_{\mathbf{n}})} \right] \end{aligned}$$
(56)

where

(41)

.....

(44) (45)

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$$k_{6} = \frac{6}{T_{e}LN_{rh}} \left( \frac{\sin 2\delta_{1}}{\delta_{1} + \sin \delta_{1}\cos \delta_{1}} (T_{1} - T_{e}) \right)^{2} / \frac{1}{\delta_{1} + \sin \delta_{1}\cos \delta_{1}} \left( \frac{1}{\delta_{1}} - \frac{1}{\delta_{1}} \right)^{2} / \frac{1}{\delta_{1}} \left( \frac{1}{\delta_{1}} - \frac{1}{\delta_$$

The solution for  $\varphi_2$  is given by (56), (50), (44) and (38), the temperature by (31), and the nondimensional temperature by

$$\frac{\mathbf{T}^{(2)} - \mathbf{T}_{\mathbf{i}}}{\mathbf{T}_{\mathbf{e}} - \mathbf{T}_{\mathbf{i}}} = 1 - \begin{bmatrix} 2 e^{-\delta_{1}^{2} \mathbf{N}_{FO}} & \frac{\sin \delta_{1} \cos(\delta_{1} \xi)}{\delta_{1} + \sin \delta_{1} \cos \delta_{1}} \\ + 2 \sum_{n=1}^{\infty} e^{-\delta_{n}^{2} \mathbf{N}_{FO}} & \frac{\sin \delta_{n} \cos(\delta_{n} \xi)}{\delta_{n} + \sin \delta_{n} \cos \delta_{n}} \end{bmatrix}$$

$$- 2 \sum_{n=1}^{\infty} \delta_n e^{-\delta_n^2 N_{FO}} \frac{\sin \delta_1 \cos(\delta_n \xi)}{(\delta_1 + \sin \delta_1 \cos \delta_1)}$$

$$\cdot \frac{1}{(\delta_n + \sin \delta_n \cos \delta_n)} \left[ \frac{\sin(\delta_1 + \delta_n)}{(\delta_1 + \delta_n)} + \frac{\sin(\delta_1 - \delta_n)}{(\delta_1 - \delta_n)} \right]$$

$$+ \sum_{n \neq 1}^{\infty} \delta_n e^{-\delta_n^2 N_{FO}} \frac{\cos(\delta_n \xi)}{(\delta_n + \sin \delta_n \cos \delta_n)}$$

$$\cdot \frac{D_1}{L(k_g \cos q_1 1 - q_1 \sin q_1 1)} \left[ \frac{\sin(\sqrt{2} \ \delta_1 + \delta_n)}{(\sqrt{2} \ \delta_1 + \delta_n)} + \frac{\sin(\sqrt{2} \ \delta_1 - \delta_n)}{(\sqrt{2} \ \delta_1 - \delta_n)} \right] - k^{(1)} \frac{\cos q_1(x) e^{-k_2 T}}{(k_g \cos q_1 1 - q_1 \sin q_1 1)}$$
(57)

where

$$D_{i} = \frac{6}{N_{rb}} \left\{ \frac{\sin 2\delta_{1}}{\delta_{1} + \sin \delta_{1} \cos \delta_{1}} \right\}^{s} \left( \frac{T_{i}}{T_{e}} - 1 \right)$$
(58)

It was empirically determined, based upon numerical computation, that the deletion of the n > 1 terms in the several infinite series of (58) caused no observable change in the temperature function.<sup>1</sup> Hence, an entirely satisfactory en-

<sup>1</sup> That is, in the range where the second approximation may be considered inadequate, the inclusion of additional terms in each infinite series does not improve the accuracy. Improvement in accuracy can be obtained only by going to a higher approximation of the perturbation solution. gineering solution is provided when only the n = 1 terms are retained, i.e.

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$$\frac{\mathbf{T}^{(\mathbf{a})} - \mathbf{T}_{\mathbf{i}}}{\mathbf{T}_{\mathbf{e}} - \mathbf{T}_{\mathbf{i}}} = 1 - \left[ 2 e^{-\delta_{1}^{2} N_{Fo}} \frac{\sin \delta_{1} \cos(\delta_{1} \xi)}{(\delta_{1} + \sin \delta_{1} \cos \delta_{1})} + (D_{\mathbf{i}}) \frac{\cos \delta_{1}}{(\delta_{1} + \sin \delta_{1} \cos \delta_{1})} \right] \\
+ (D_{\mathbf{i}}) \frac{\cos \delta_{1}}{(\delta_{1} + \sin \delta_{1} \cos \delta_{1})} \\
\cdot \frac{e^{-\delta_{1}^{2} N_{Fo}}}{(\frac{\mu}{N_{Fh}} \cos/2 \delta_{1} - \sqrt{2} \delta_{1} \sin/2 \delta_{1})} \\
\cdot \left\{ \frac{\sin(\sqrt{2} + 1)\delta_{1}}{(\sqrt{2} + 1)} + \frac{\sin(\sqrt{2} - 1)\delta_{1}}{(\sqrt{2} - 1)} \right\} \\
- \frac{(D_{\mathbf{i}}) \cos(\sqrt{2} \delta_{1} \xi) e^{-2\delta_{1}^{2} N_{Fo}}}{(\frac{\mu}{N_{Fh}} \cos/2 \delta_{1} - \sqrt{2} \delta_{1} \sin/2 \delta_{1})} \right] (59)$$

This completes the solution for the second approximation.

Third Approximation Proceeding as in the second approximation let

$$\varphi_3 = \zeta(\mathbf{x}, \tau) + f_1 g_1 + f_2 g_2 \tag{60}$$

After substitution and identifying  $f_2$  and  $g_2$  with suitable nonhomogeneous terms, it is found that  $f_2$  is the solution of the same boundary value problem governing  $f_1$  but where the coefficient  $k_2$  is replaced by  $3/2 k_2$ . The non-dimensional solution turns out to be

$$\begin{split} \frac{\Gamma(3)-T_{4}}{\Gamma_{g}-T_{1}} &= 1 \left| -\left[ 2 \ G_{1} \sin \delta_{1} \cos(\delta_{1}\xi) e^{-\delta_{1}^{2}N_{FO}} \right. \\ &+ \ G_{1} C_{2} C_{3} (D_{1}) Gos(\delta_{1}\xi) e^{-\delta_{1}^{2}N_{FO}} \\ &- \ C_{2} (D_{1}) Gos(\sqrt{2} \ \delta_{1}\xi) e^{-\delta_{1}^{2}N_{FO}} + 2 \ \sum_{n=1}^{\infty} e^{-\delta_{n}^{2}N_{FO}} \\ &\cdot \ \frac{Cos(\delta_{n}\xi) Sin \ \delta_{n}}{(\delta_{n}+Sin \ \delta_{n}Cos \ \delta_{n})} - 2 \ C_{1} \sum_{n=1}^{\infty} \delta_{n} \ e^{-\delta_{n}^{2}N_{FO}} \\ &\cdot \ \frac{Cos(\delta_{n}\xi) Sin \ \delta_{n}}{(\delta_{n}+Sin \ \delta_{n}Cos \ \delta_{n})} \left\{ \frac{Sin(\delta_{1}+\delta_{n})}{(\delta_{1}+\delta_{n})} + \frac{Sin(\delta_{1}-\delta_{n})}{(\delta_{1}-\delta_{n})} \right\} \\ &- \ C_{1} C_{2} C_{3} (D_{1}) \sum_{n=1}^{\infty} \delta_{n} \ e^{-\delta_{n}^{2}N_{FO}} \\ &\cdot \ \frac{Cos(\delta_{n}\xi)}{(\delta_{n}+Sin \ \delta_{n}Cos \ \delta_{n})} \left\{ \frac{Sin(\delta_{1}+\delta_{n})}{(\delta_{1}+\delta_{n})} + \frac{Sin(\delta_{1}\ \delta_{n})}{(\delta_{1}-\delta_{n})} \right\} \\ &+ \ C_{3} C_{3} \sum_{n=1}^{\infty} e^{-\delta_{n}^{2}N_{FO}} \ \frac{Cos(\delta_{n}\xi)}{(\delta_{n}+Sin \ \delta_{n}Cos \ \delta_{n})} \\ &+ \ 2 \ C_{1} C_{2} C_{3} C_{4} \sum_{n=1}^{\infty} \delta_{n} \ e^{-\delta_{n}^{2}N_{FO}} \ \frac{Cos(\delta_{n}\xi)}{\delta_{n}+Sin \ \delta_{n}Cos \ \delta_{n}} \\ &+ \ 2 \ C_{1} C_{2} C_{3} C_{4} \sum_{n=1}^{\infty} \delta_{n} \ e^{-\delta_{n}^{2}N_{FO}} \ \frac{Cos(\delta_{n}\xi)}{\delta_{n}+Sin \ \delta_{n}Cos \ \delta_{n}} \\ &+ \ 2 \ \frac{Sin(\sqrt{2} \ \delta_{1}-\delta_{n})}{N_{Fh}} \right] - \frac{2}{3} \ C_{2} C_{4} \sum_{n=1}^{\infty} \delta_{n} \ e^{-\delta_{n}^{2}N_{FO}} \end{aligned}$$

$$\frac{\cos(\delta_{n}\xi)}{(\delta_{n}+\sin \delta_{n}\cos \delta_{n})} (D_{1}) \left\{ \frac{\sin(\sqrt{3} \delta_{1}+\delta_{n})}{(\sqrt{3} \delta_{1}-\delta_{n})} + \frac{\sin(\sqrt{3} \delta_{1}-\delta_{n})}{(\sqrt{3} \delta_{1}-\delta_{n})} \right\} \left\{ \frac{18}{N_{rh}} C_{2}\cos(\sqrt{2} \delta_{1}\xi) - 1 \right\}$$

$$- \frac{12}{N_{rh}} C_{1}C_{2}C_{3}C_{4}(D_{1})\cos \delta_{1}\cos(\sqrt{2} \delta_{1}\xi) e^{-2\delta_{1}} N_{Fo}$$

$$+ \frac{2}{3} C_{4}(D_{1}) \left\{ \frac{18}{N_{rh}}C_{2}\cos(\sqrt{2} \delta_{1}\xi) - 1 \right\}$$

$$+ \left\{ e^{-3\delta_{1}^{2}N_{Fo}}\cos(\sqrt{3} \delta_{1}\xi)C_{5} \right\} \right]$$

$$+ \left\{ e^{-3\delta_{1}^{2}N_{Fo}}\cos(\sqrt{3} \delta_{1}\xi)C_{5} \right\} \right]$$

$$+ \left\{ e^{-3\delta_{1}^{2}N_{Fo}}\cos(\sqrt{3} \delta_{1}\xi)C_{5} \right\}$$

$$+ \left\{ e^{-3\delta_{1}^{2}N_{Fo}}\cos(\sqrt{3} \delta_{1}\xi)C_{5} \right\} \right]$$

$$+ \left\{ e^{-3\delta_{1}^{2}N_{Fo}}\cos(\sqrt{3} \delta_{1}\xi)C_{5} \right\}$$

$$+ \left\{ e^{-3\delta_{1}^{2}N_{Fo}}\cos(\sqrt{3} \delta_{1}\xi)C_{5}$$

$$\frac{T^{(3)} - T_{i}}{T_{e} - T_{i}} = 1 - \left[ 2 C_{1} \sin \delta_{1} \cos(\delta_{1}\xi) e^{-\delta_{1}^{2}N_{FO}} \right]$$

$$- C_{2} (D_{1}) \cos(\sqrt{2} \delta_{2}\xi) e^{-\delta_{1}^{2}N_{FO}}$$

$$+ C_{1} C_{2} C_{3} \cos \delta_{1}\xi e^{-\delta_{1}^{2}N_{FO}}$$

$$+ \frac{12}{N_{rh}} C_{1}^{2} C_{2} C_{3}^{2} C_{4} (D_{1}) \cos \delta_{1} \cos(\delta_{1}\xi)$$

$$\cdot e^{-\delta_{1}^{2}N_{FO}} - \frac{2}{3} C_{1} C_{2} C_{4} C_{6} (D_{1}) \cos(\delta_{1}\xi)$$

$$\cdot \left\{ \frac{\sin(\sqrt{3}+1)\delta_{1}}{(\sqrt{3}+1)} + \frac{\sin(\sqrt{3}-1)\delta_{1}}{(\sqrt{3}-1)} \right\}_{e} -\delta_{1}^{2}N_{FO}}$$

$$- \frac{12}{N_{rh}} C_{1} C_{2} C_{3} C_{4} (D_{1}) \cos \delta_{1} \cos(\sqrt{2} \delta_{1}\xi)$$

$$\cdot e^{-2\delta_{1}^{2}N_{FO}} + \frac{2}{3} C_{4} C_{5} C_{6} (D_{1}) \cos(\sqrt{3} \delta_{1}\xi)$$

$$\cdot e^{-3\delta_{1}^{2}N_{FO}} \right]$$

$$(62)$$

This completes the solution for the third approximation.

n<sup>th</sup> Approximation The n<sup>th</sup> approximation is ob-tained in an analogous manner by writing

$$\varphi_n = \zeta(x,\tau) + f_1 g_1 + f_2 g_3 + \cdots + f_{n-1} g_{n-1}$$
 (63)

which results in a set of equations for the "f" functions as follows:

$$\alpha f_{1}^{"}(\mathbf{x}) g_{1}(\tau) - f_{2}(\mathbf{x}) g_{1}(\tau) = 0$$

$$f_{1}^{'}(0) = 0$$

$$f_{1}^{'}(\mathbf{L}) + k_{5}f_{1}(\mathbf{L}) = 1, \text{ where } g_{1}(\tau) = -k^{(1)}e^{-k_{2}\tau}$$
(64)
$$\alpha f_{2}^{"}(\mathbf{x}) g_{2}(\tau) - f_{2}(\mathbf{x}) g_{2}^{*}(\tau) = 0$$

$$f_{2}^{'}(0) = 0$$

$$f_{2}^{'}(\mathbf{L}) + k_{5}f_{2}(\mathbf{L}) = 1, \text{ where } g_{2}(\tau) = -k^{(2)}e^{-3/2k_{2}\tau}$$
(65)
$$\alpha f_{n-1}^{"}g_{n-1} - f_{n-1}g_{n-1}^{*} = 0$$

$$f_{n-1}^{'}(0) = 0$$

$$f_{n-1}^{'}(\mathbf{L}) + k_{5}f_{n-1}(\mathbf{L}) = 1, \text{ where } g_{n-1}(\tau) = -k^{(n-1)}e^{-(n/2)k_{2}\tau}$$
(66)

These are easily solved to yield

$$\mathbf{f_1}(\mathbf{x}) = \frac{\cos(q_1\mathbf{x})}{(k_g \cos q_1 l - q_1 \sin q_1 l)} \text{ where } q_1 = \frac{k_2}{\alpha} (67)$$

$$\mathbf{f_2}(\mathbf{x}) = \frac{\cos q_2(\mathbf{x})}{(k_g (\cos q_2 l - q_2 \sin q_2 l))} \text{ where } q_2 = \sqrt{\frac{3k_2}{2\alpha}}$$

$$\mathbf{f_{n-1}}(\mathbf{x}) = \frac{\cos(q_1 \frac{\mathbf{x}}{\mathbf{x}_{-1}})}{(k_g \cos q_1 l - q_{n-1} \sin q_{n-1})}$$

$$\mathbf{where } q_{n-1} = \sqrt{\frac{n}{2}} (28) (69)$$

Hence  $\varphi_n(62)$  is given by

$$p_{n} = \zeta + \frac{\cos(q_{1}x)}{(k_{5}\cos q_{1}l-q_{1}\sin q_{1}l)} (-k^{(1)} e^{-k_{2}\tau}) + \frac{\cos(q_{2}x)}{(k_{5}\cos q_{2}l-q_{2}\sin q_{2}l)} (-k^{(2)} e^{-\frac{3}{2}k_{3}\tau}) + \frac{\cos(q_{n-1}x)}{(k_{5}\cos q_{n}l-q_{2}-1)} (-k^{(n-1)} e^{-\frac{n}{2}k_{2}\tau}) (70)$$

and the corresponding initial condition is

$$\varphi_{n}(\mathbf{x},0) = \zeta_{n-1}(\mathbf{x},0) + f_{1}(\mathbf{x})g_{1}(0) + \dots + f_{n-1}(\mathbf{x})g_{n-1}(0)$$
(71)

The function  $\zeta(\mathbf{x},\tau)$  is obtained in the usual way for this new initial condition, thus completing the  $n^{\rm th}$  approximation.

<u>Comparison with Analog Computer Results</u>: By use of the formulas developed it is possible to compute numerical values simply by slide rule, and, in fact, data for several curves were computed in this manner. However, because it was felt desirable to compare the perturbation solutions with the curves obtained by analog computer in

ref. (7) (which are quite numerous) most of the numerical calculations were performed on an IBM 7040 and the results plotted with the help of Calcomp. 545. There are several key parameters and various arrangements are possible for plotting purposes. The scheme chosen follows ref. (7). The basic parameter is  $T_i/T_e$ ; values are plotted for 0.75, 0.5, 0.25. For each  $T_i/T_e$ , three stations were chosen, x/L = 0, 0.5, 1.0. Finally for a given value of  $T_i/T_e$  and x/L, curves of non-dimensional temperature  $(T-T_i)/(T_e-T_i)$  versus non-dimensional time  $\alpha \tau/L^2$  are plotted for three values of the parameter Nrh. These are plotted in Figures (1), (2), (3). It is found that for  $T_{i}T_{e} = 0.75$  the first approximation is quite accurate and the second approximation gives the values very close to that obtained by ref. (7) so that this approximation may be satisfactory for engineering applications. As the ratio  $T_i/T_e$ is reduced to 0.5, it is seen that third approximation is quite close to the analog computer results. As expected the results for  $T_{\rm i}/T_{\rm e}$  = 0.25 do not compare quite as favorably to ref. (7) as do the higher ratios but, nevertheless, should be of sufficient accuracy for most applications.

<u>Conclusion</u> It has been demonstrated foregoing that a perturbation technique yields a satisfactory approximation to the nonlinear radiation heating problem. Numerical results computed by the formulas developed compare quite favorably to previously obtained analog results for a  $T_i/T_e$  as small as 0.25.

One major advantage of an analytical solution over an analog (or digital) computer solution is that values of interest may be obtained without the need for interpolating between plotted values or chart values. To obtain the flux, for example, by means of the analog computer solution in general, requires obtaining differences between two curves which are a small distance apart. With the data given in ref. (7) however, one would have to interpolate between values given at x/L = 1, x/L = 0.5, and x/L = 0. On the other hand to obtain the flux by means of the solution developed herein requires only the differentiation of (61). The third approximation for the flux is indicated below.

$$\begin{split} \frac{L}{T_{e}-T_{1}} \frac{\partial T}{\partial x} \bigg|_{x=L} &= \delta_{1} e^{-\delta_{1}^{2}N_{FO}} [2 \ C_{1} \sin \delta_{1} \cos \delta_{1} \\ &- \sqrt{2} \ C_{2} (D_{1}) \sin(/2 \ \delta_{1}) + C_{1} C_{2} C_{3} Sin(\delta_{1}) \\ &+ \frac{12}{N_{rh}} \ C_{1}^{2} C_{2} C_{3}^{2} C_{4} (D_{1}) Sin \ \delta_{1} \cos \delta_{1} \\ &- \frac{2}{3} \ C_{1} C_{2} C_{4} C_{6}^{\prime} (D_{1}) Sin(\delta_{1}) \left\{ \frac{Sin(\sqrt{3}+1)\delta_{1}}{\sqrt{3}+1} \right\} \\ &+ \frac{Sin(\sqrt{3}-1)\delta_{1}}{(\sqrt{3}-1)} \right\} + \frac{12/2}{N_{rh}} \ C_{1} C_{2}^{2} C_{4} (D_{1}) \\ &Sin(\sqrt{2} \ \delta_{1}) Cos(\delta_{1}) \left\{ \frac{Sin(\sqrt{3}+1)\delta_{1}}{(\sqrt{3}+1)} \right\} \\ &+ \frac{Sin(\sqrt{3}-1)\delta_{1}}{(\sqrt{3}-1)} - \frac{12/2}{N_{rh}} \ C_{1} C_{2} C_{3} C_{4} (D_{1}) \end{split}$$

• 
$$\sin(\sqrt{2} \ \delta_1) \cos(\delta_1) e^{-\delta_1^2 N_{FO_+}} \frac{2}{\sqrt{3}} C_4 C_5 C_6'(D_1)$$
  
•  $\sin(\sqrt{3} \ \delta_1) e^{-2\delta_1^2 N_{FO_-}} \frac{12/2}{N_{rh}} C_2 C_4 C_5 (D_1)$   
•  $\sin(\sqrt{2} \ \delta_1) \cos(\sqrt{3} \ \delta_1) e^{-2\delta_1^2 N_{FO_-}}$   
where  $C_6' = \{18/N_{rh} \ C_2 \cos(\sqrt{3} \ \delta_1) - 1\}$  (72)

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## Nomenclature

- c = specific heat, Btu/1b deg R Fse = radiation interchange factor between slab
- and environment
- L = slab width, Ft.
- **NFo** = Fourier number,  $\alpha \tau_{1}/L^{2}$ , dimensionless **Nrh** = radiation number for heating,  $k/\sigma$  F<sub>se</sub>Te<sup>3</sup> L,
- dimensionless
- **T** = absolute temperature, deg R
- Te = environment temperature, deg R
- Ti = initial slab temperature, deg R
- x = space coordinate normal to slab faces, ft.  $\alpha$  = thermal diffusivity, k/pc, ft. <sup>2</sup>/hr.
- $\Delta T$  = temperature difference, deg R

 $\Delta x$  = distance increment in x-direction, ft.  $\Delta \tau$  = increment in time, hr.

 $\rho$  = density, lb/ft<sup>3</sup>

 $\sigma$  = Stefan-Boltzman constant, Btu/hr. ft<sup>3</sup> deg R<sup>4</sup> subscripts:

- e = refers to environment
  - i = refers to initial conditions







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